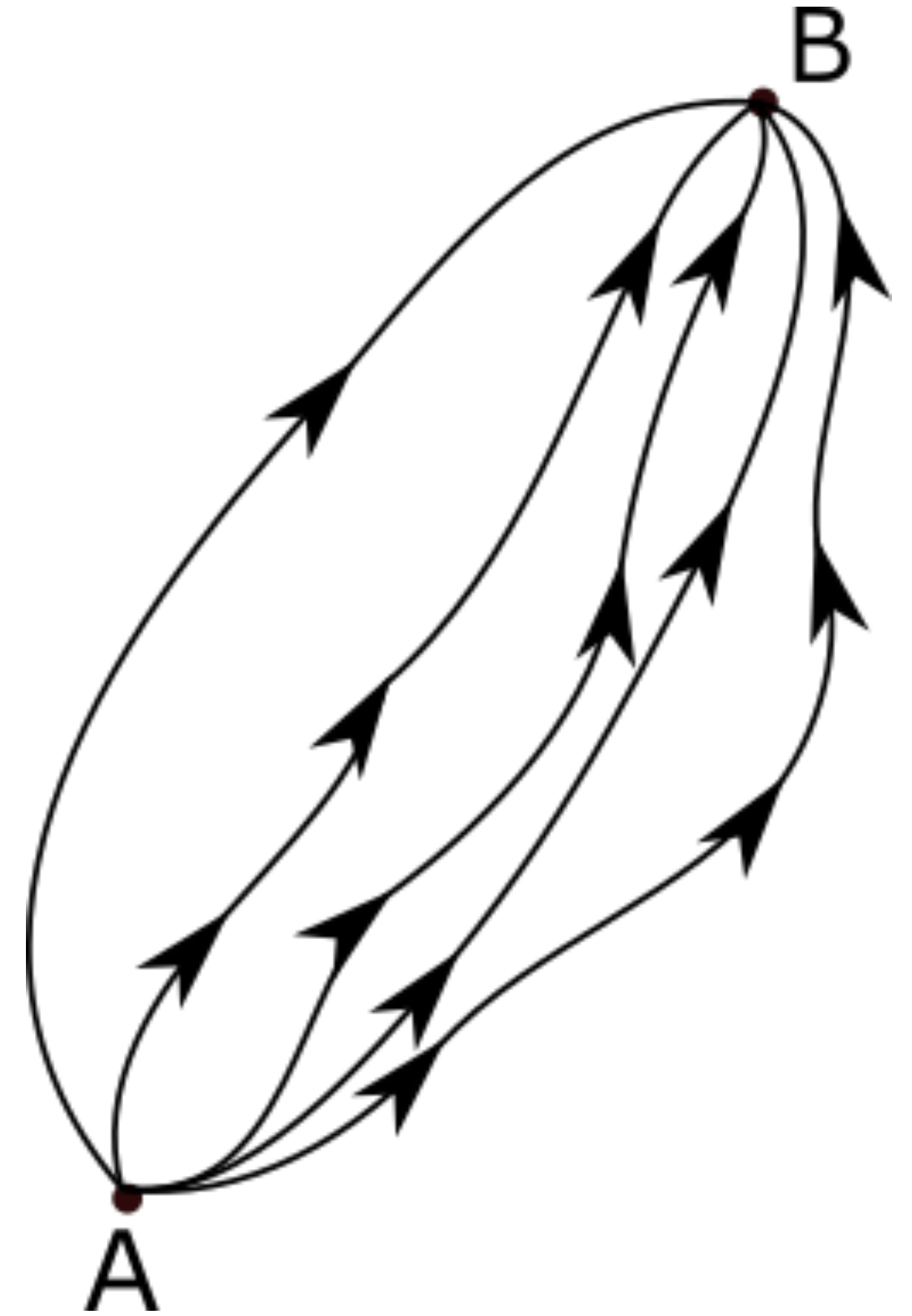


PHYS 142/242

Lecture 02: Feynman Path Integral (Continued)

Javier Duarte — January 12, 2024

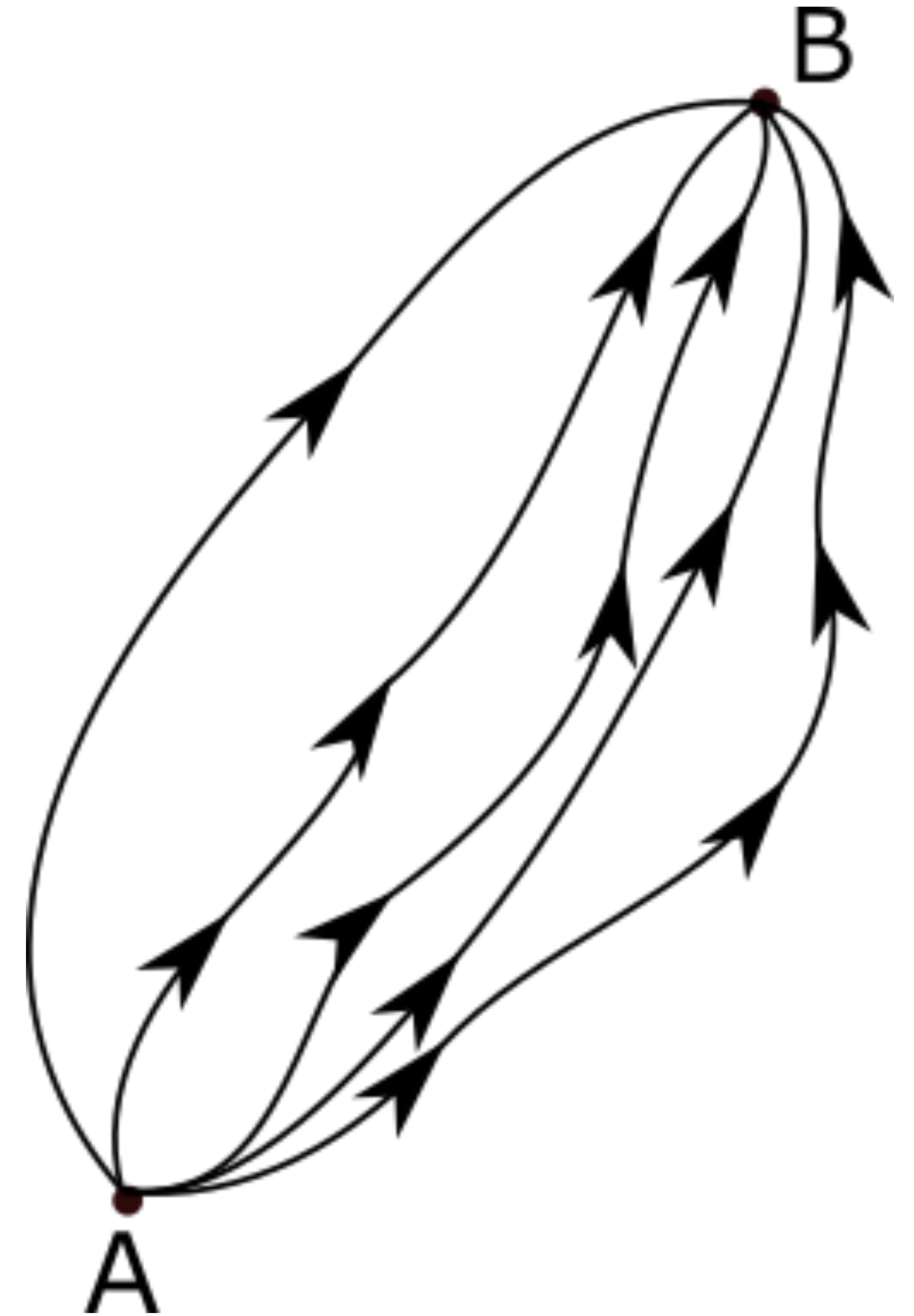
Feynman path integral



Feynman path integral

- In quantum mechanics, the amplitude to go from A to B is the sum of contributions $\phi[x(t)]$ from each path

$$K(B, A) = \sum_{\text{paths from A to B}} \phi[x(t)]$$



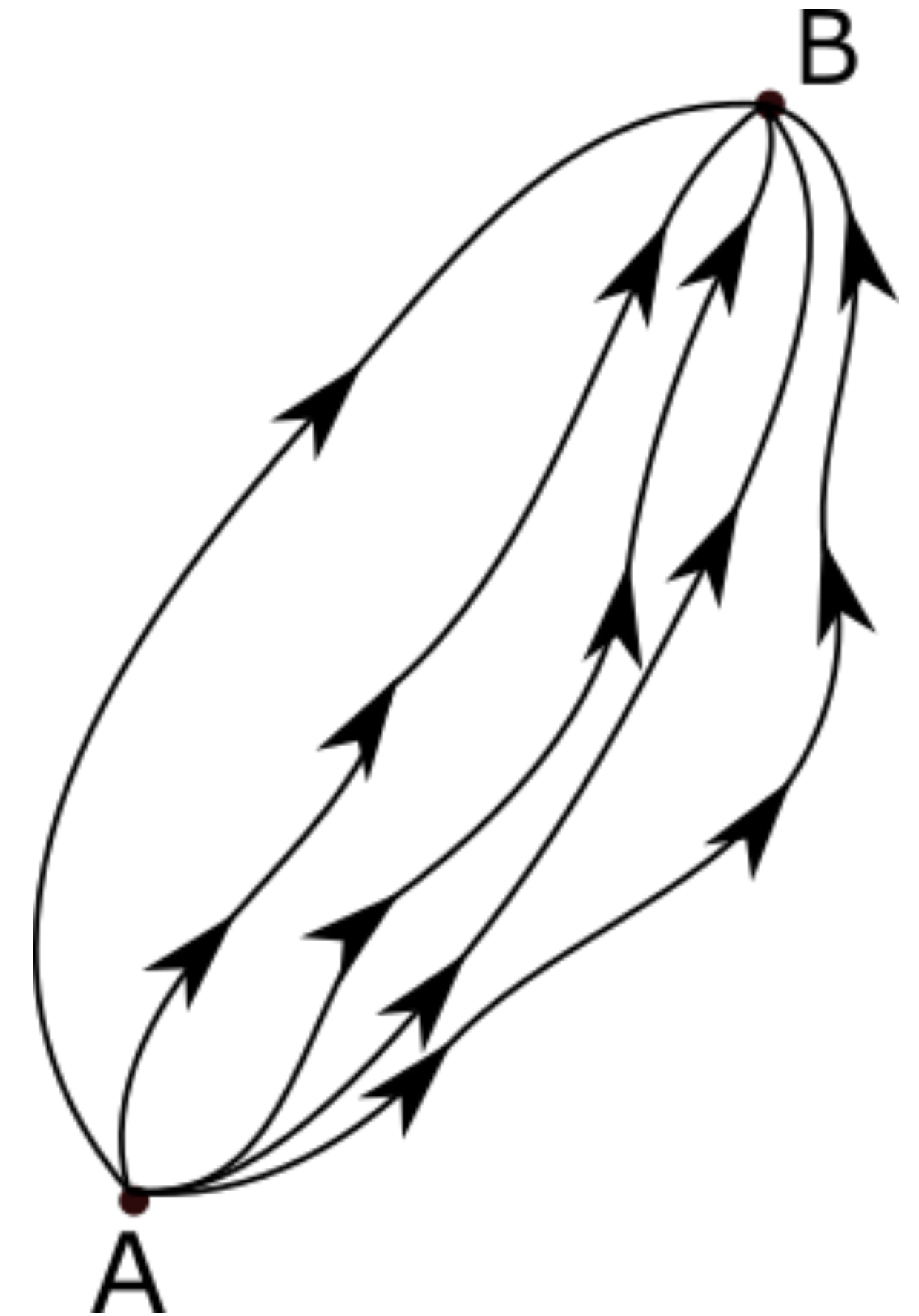
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- $\phi[x(t)] = (\text{const})e^{(i/\hbar)S[x(t)]}$



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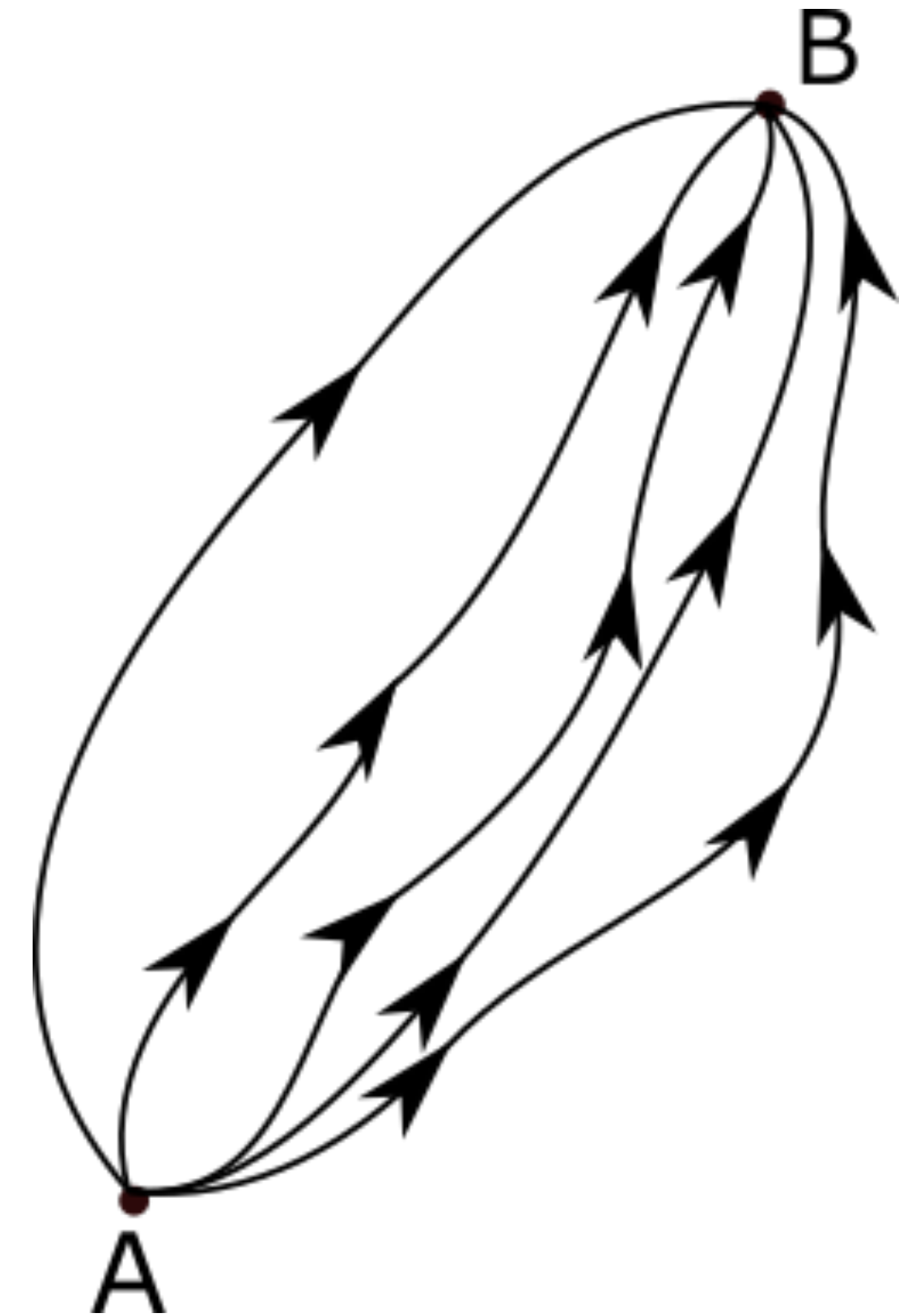
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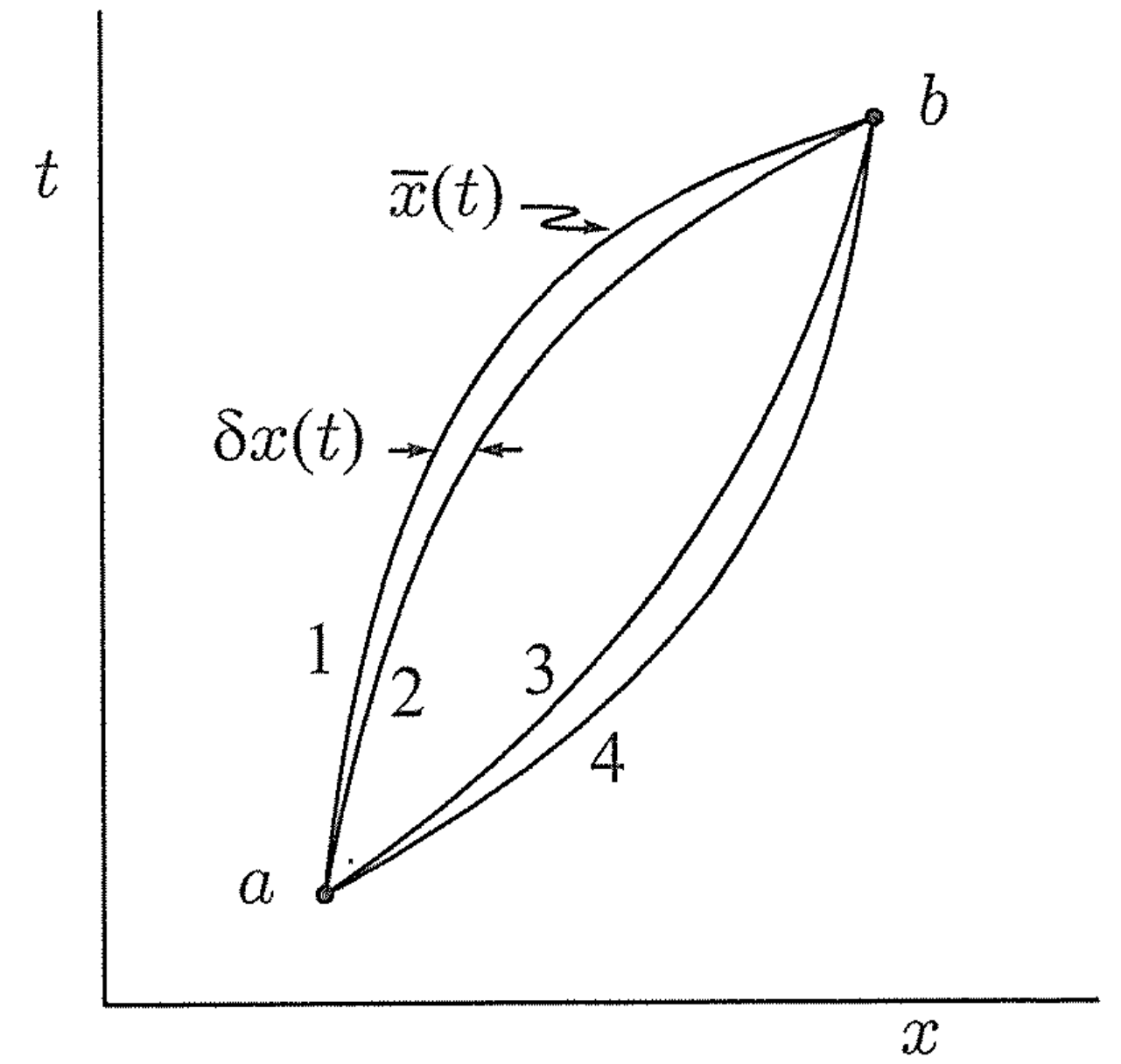
- $\phi[x(t)] = (\text{const})e^{(i/\hbar)S[x(t)]}$

- This is a generalization of the classical principle of least action, sometimes called the **quantum action principle**

- Contains the classical principle in the limit $\hbar \rightarrow 0$ (or equivalently when $S \gg \hbar$)

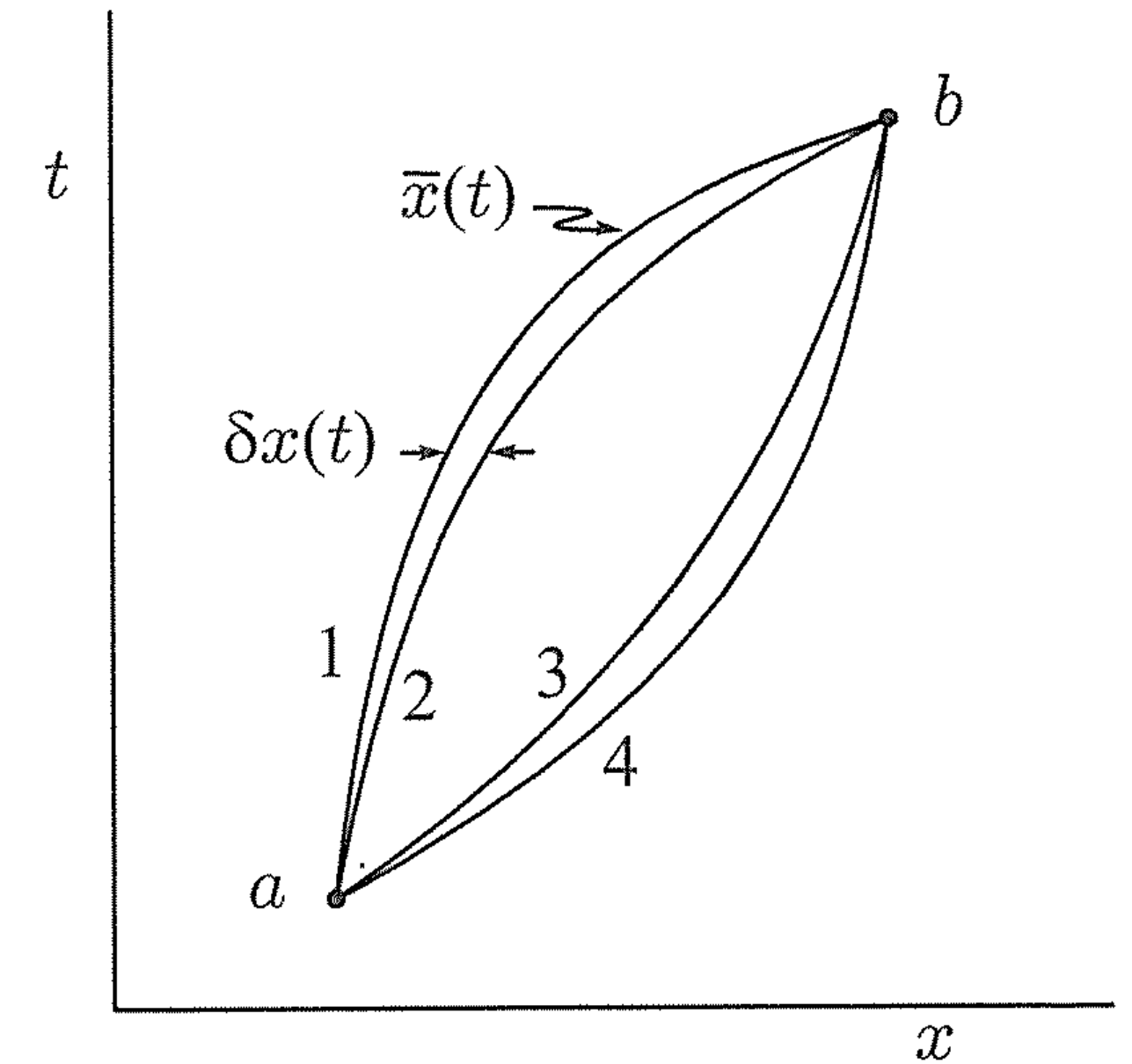


Classical limit



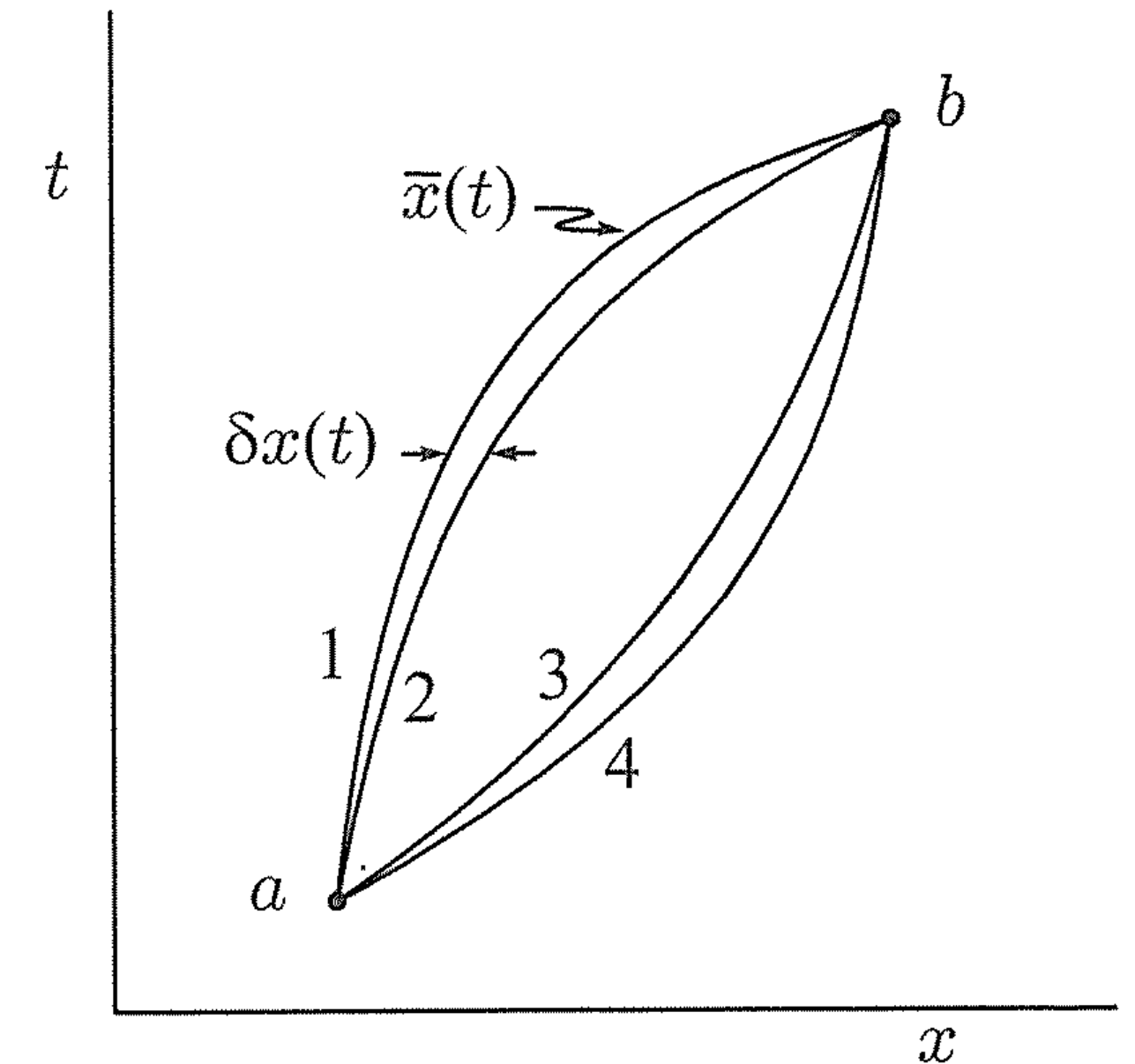
Classical limit

- The phase of each contribution is $e^{iS/\hbar} = \cos(S/\hbar) + i \sin(S/\hbar)$
 - Reminder: $\hbar = 6.6261 \times 10^{-27} \text{ cm}^2 \text{ g/s}$ (tiny!)



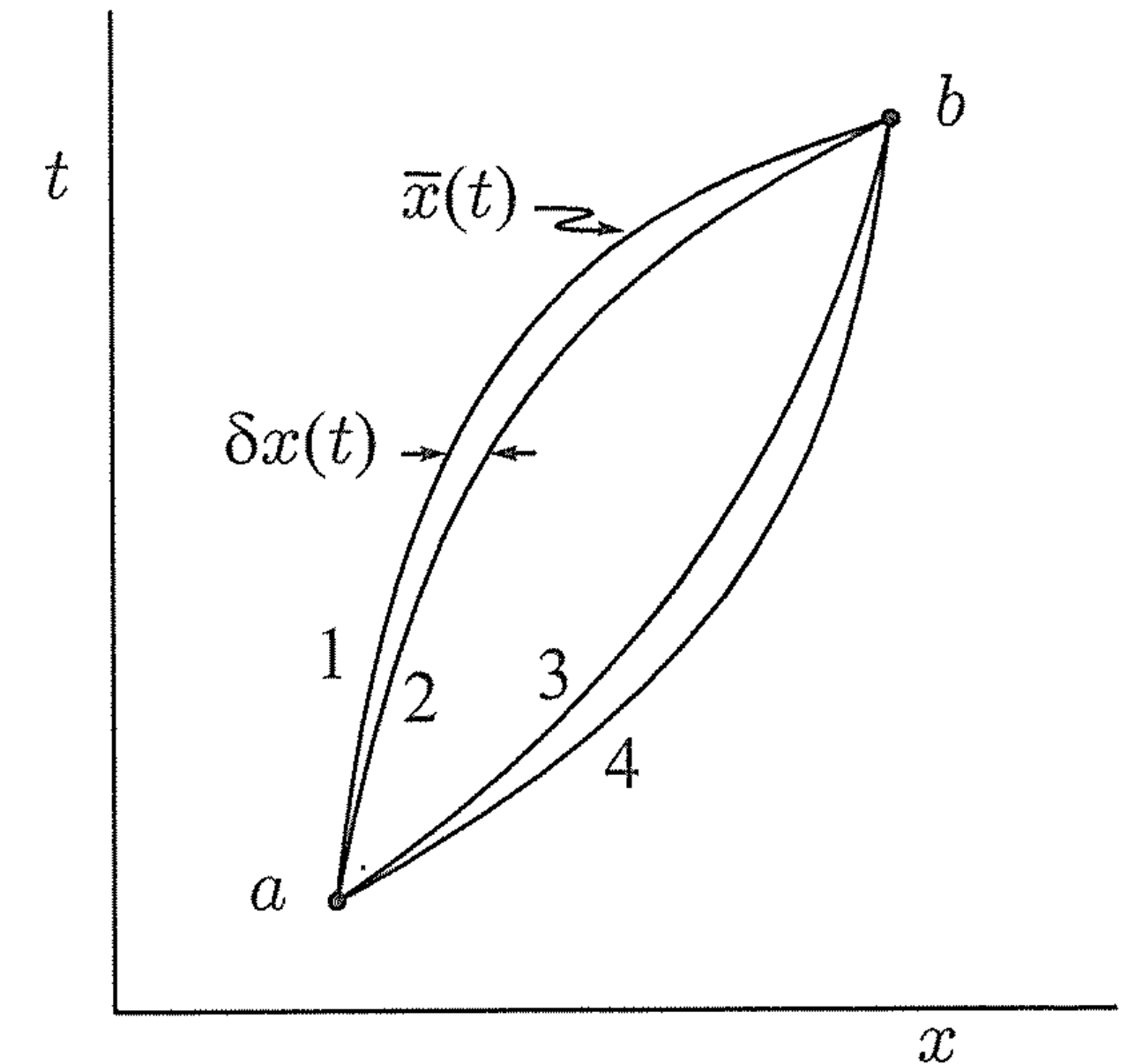
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 - e.g. 1 and 2 contribute with the same phase and ***constructively interfere***



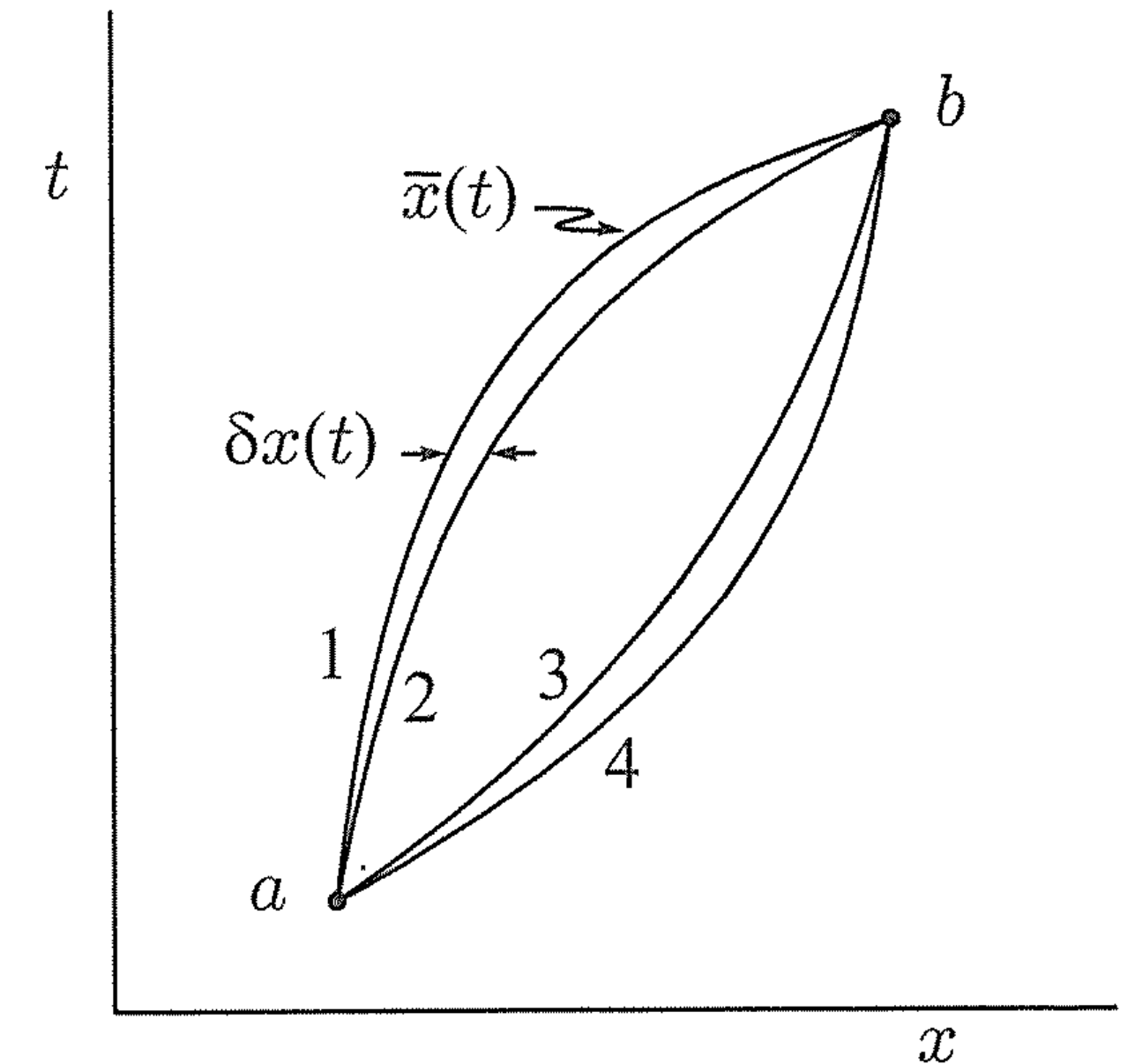
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- Far from the classical path, S varies a lot in units of $\hbar$
 - e.g. 3 and 4 contribute with different phases and ***destructively interfere***
- Only paths in the vicinity of $\bar{x}(t)$ have important contributions (that don't cancel), and ***in the classical limit we only need to consider this trajectory***
 - Classical laws of motion arise from the quantum laws!



Defining the path integral

Defining the path integral

- How do we construct the path integral/sum?

- $K(x_B, t_B; x_A, t_A) = (\text{const}) \sum_{\text{all paths}} e^{\frac{i}{\hbar} S_{\text{path}}}$

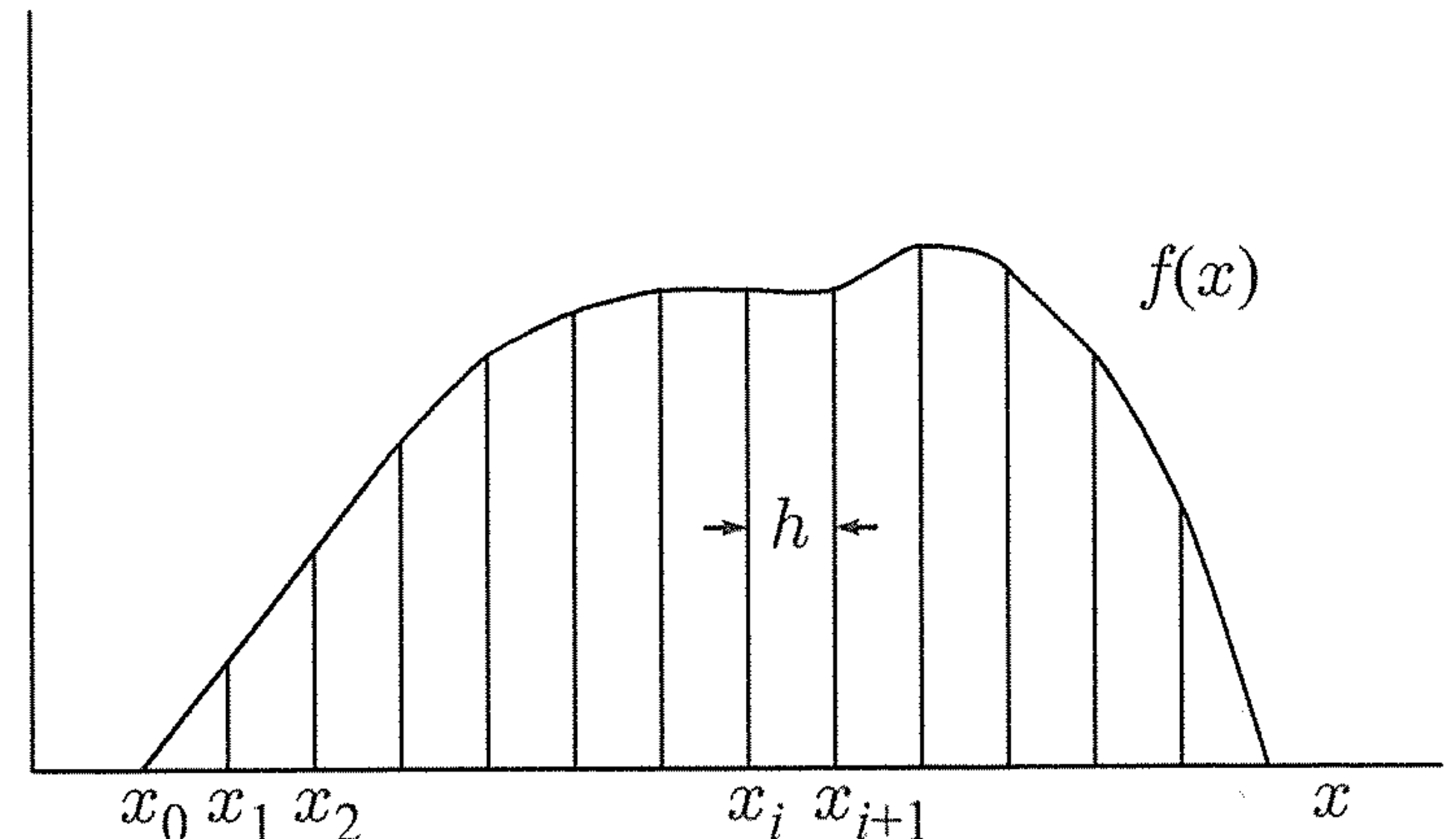
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Defining the path integral

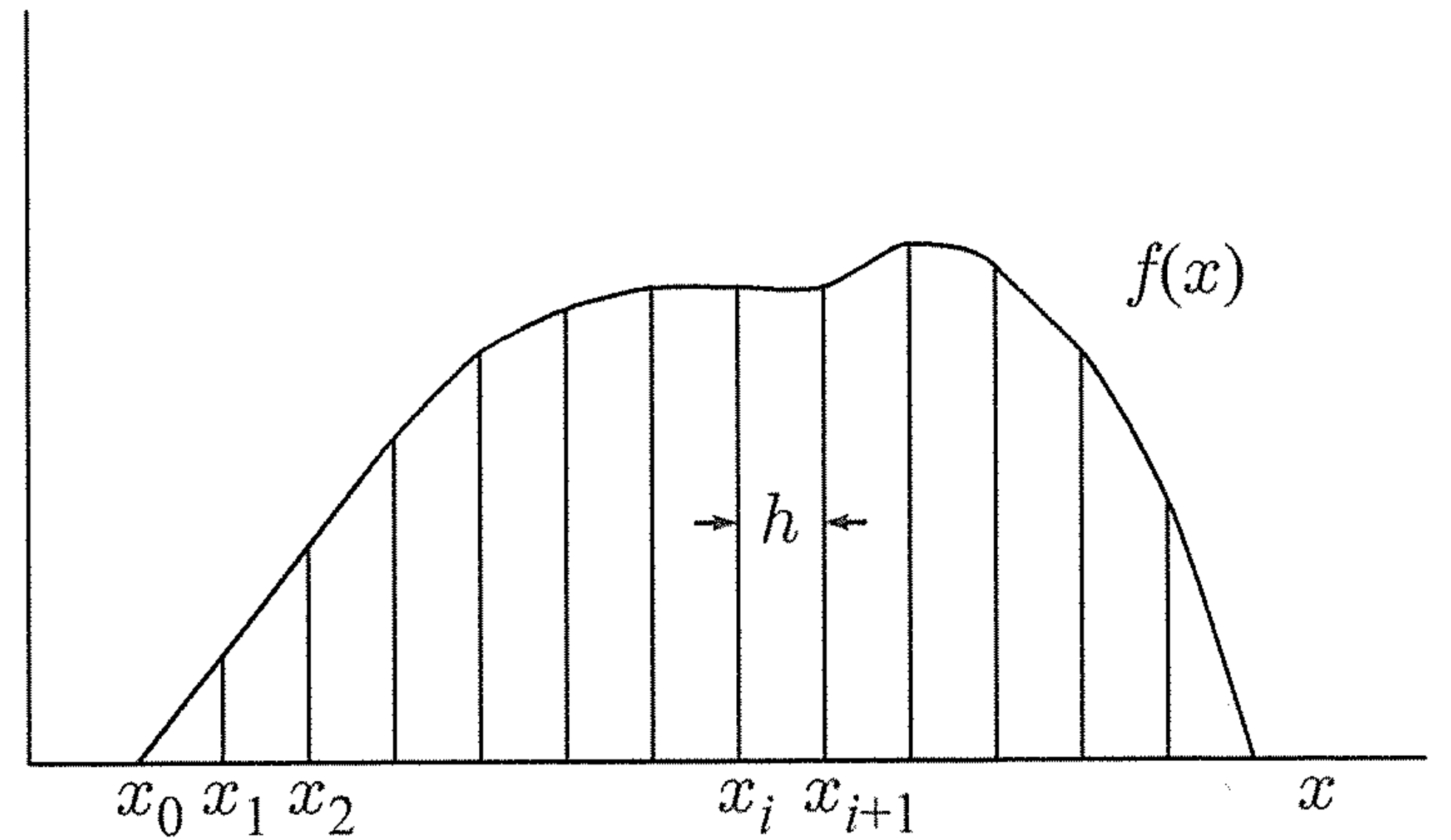
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- By analogy with the Riemann integral/sum



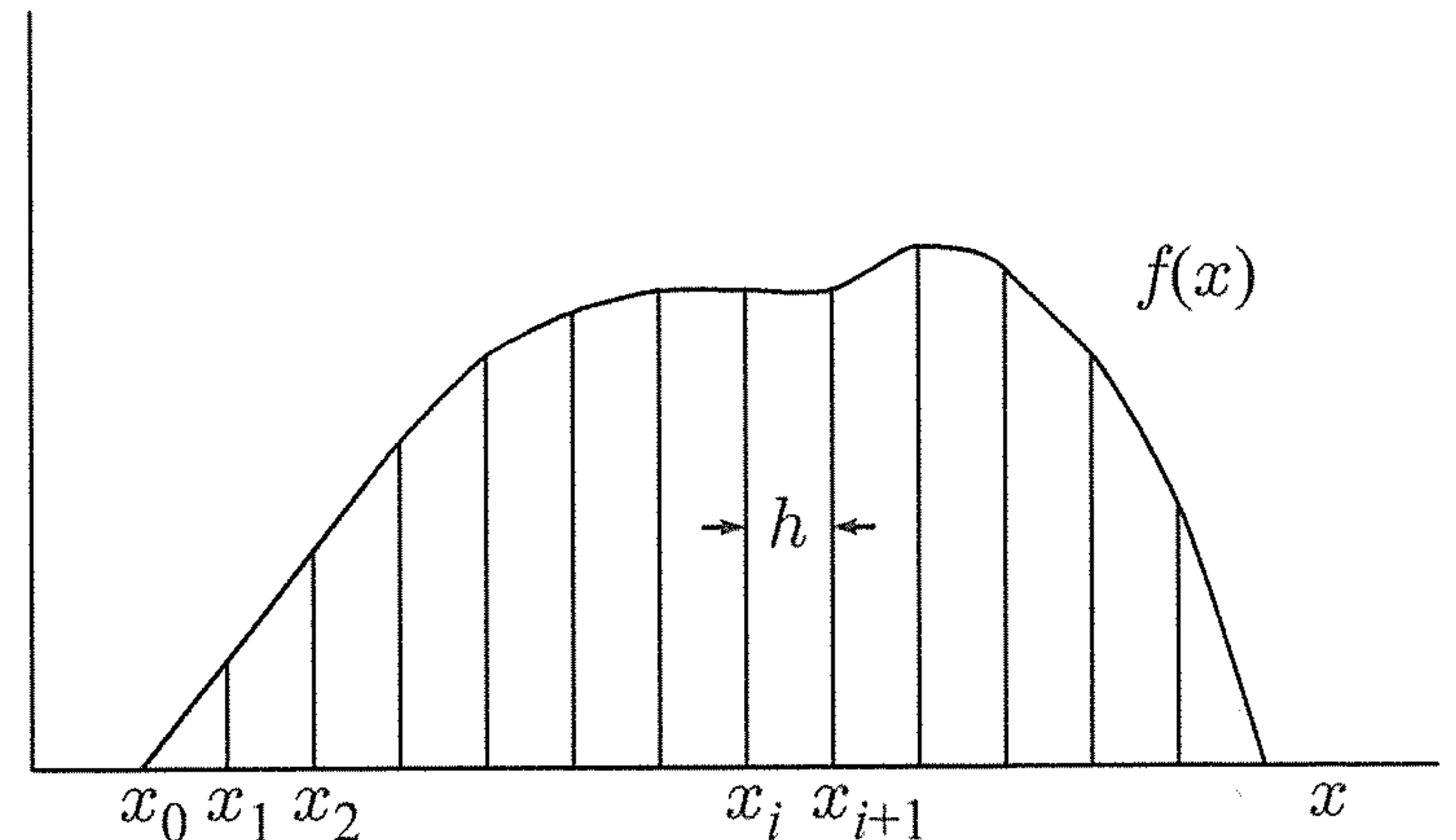
Riemann sum



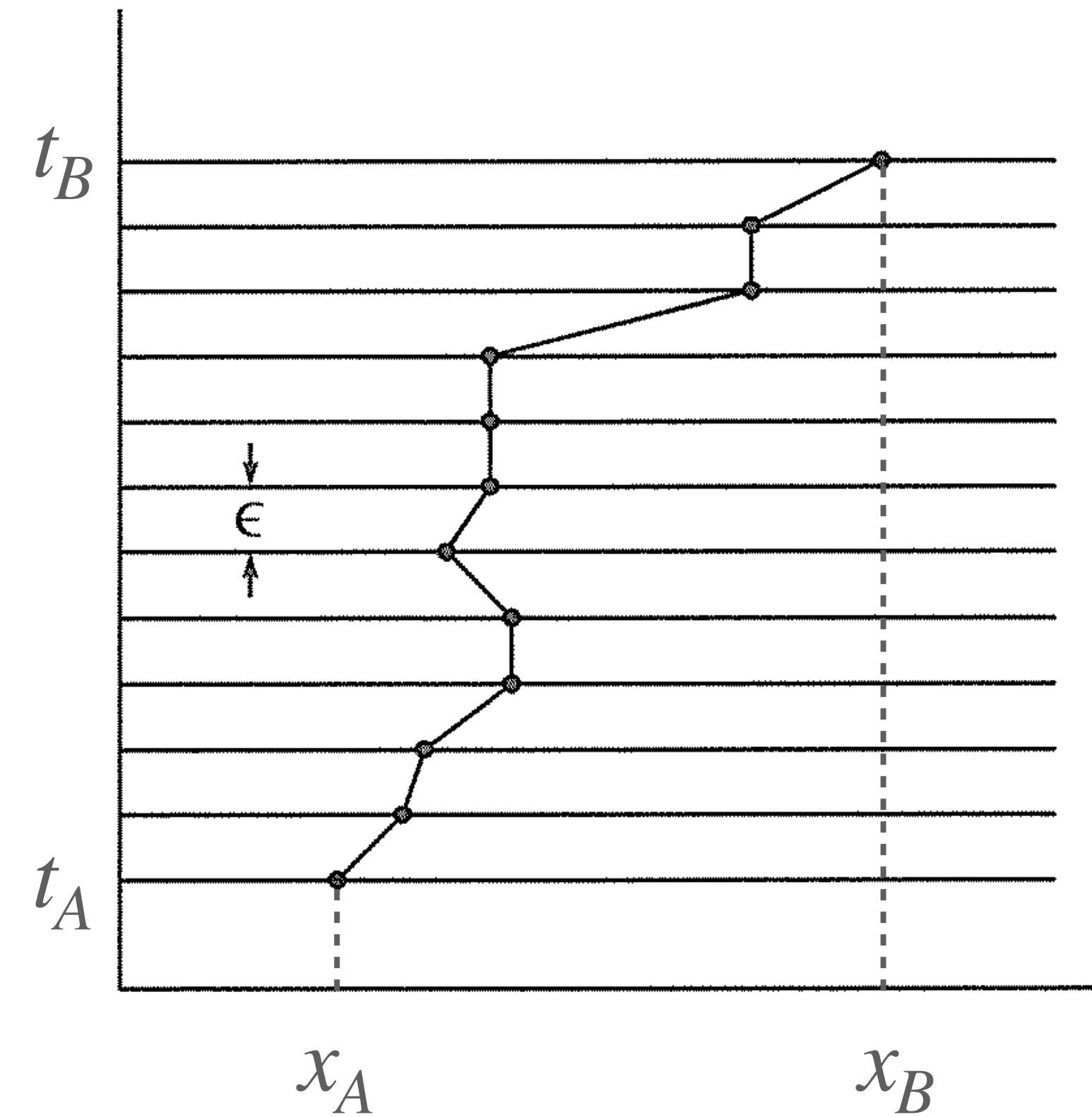
Riemann sum

- Define N equally spaced x coordinates (separation h) as a representative subset of all coordinates
- Area under the curve A is the sum of all function values evaluated at each x_i , multiplied by an overall normalization factor h ,

$$A = \lim_{h \rightarrow 0, N \rightarrow \infty} h \sum_{i=0}^{N-1} f(x_i)$$

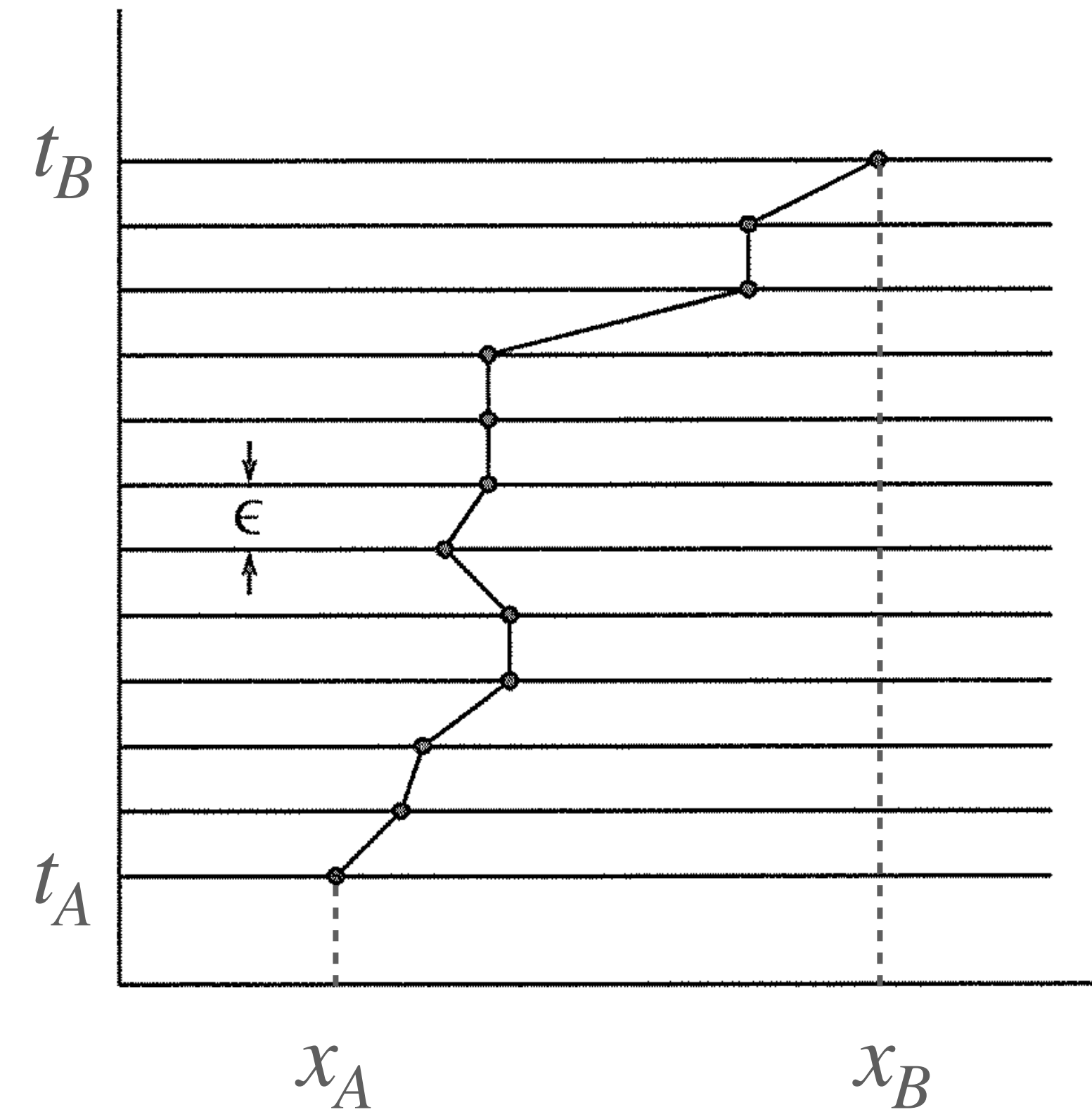


Defining the path integral



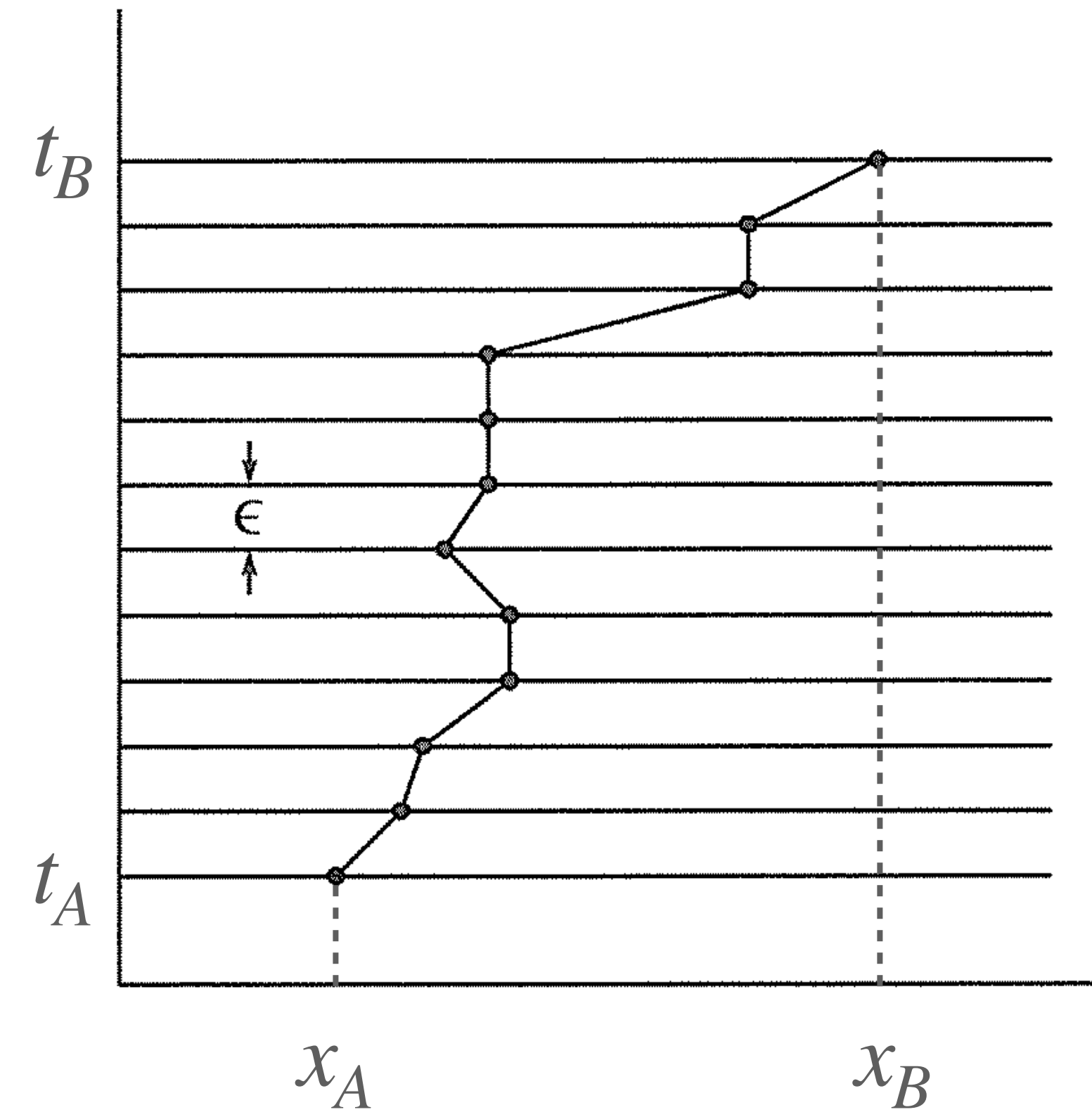
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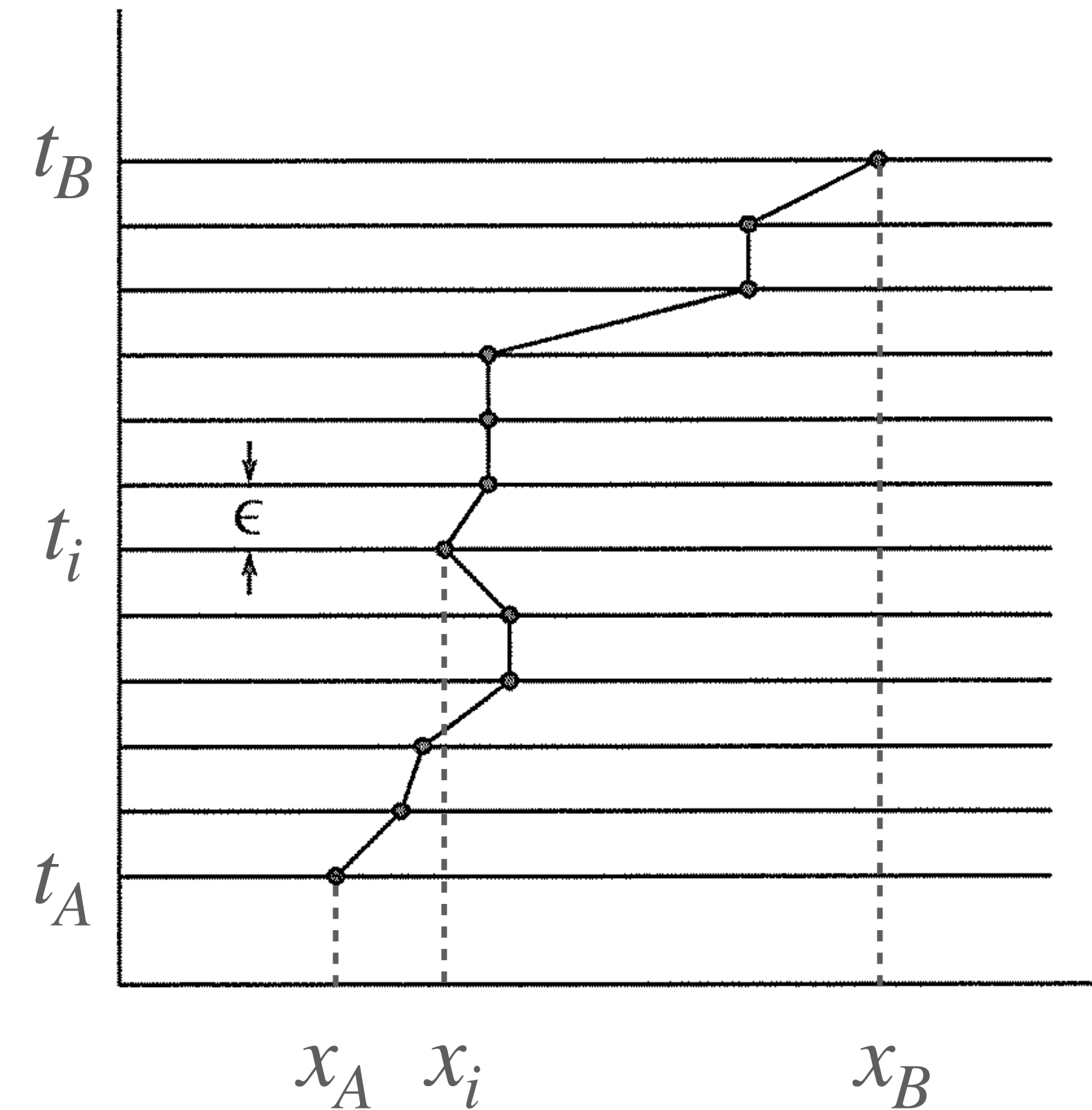
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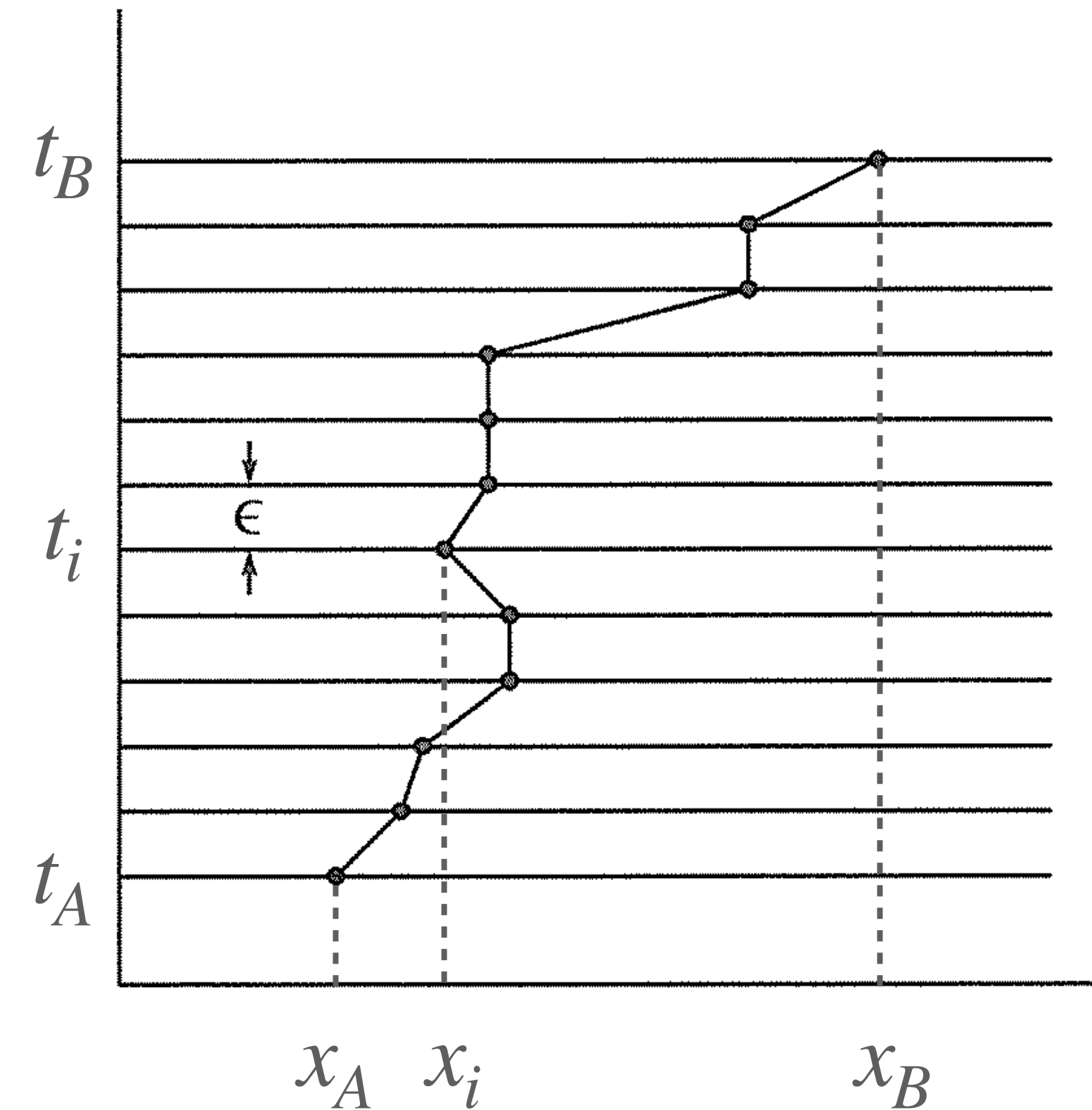
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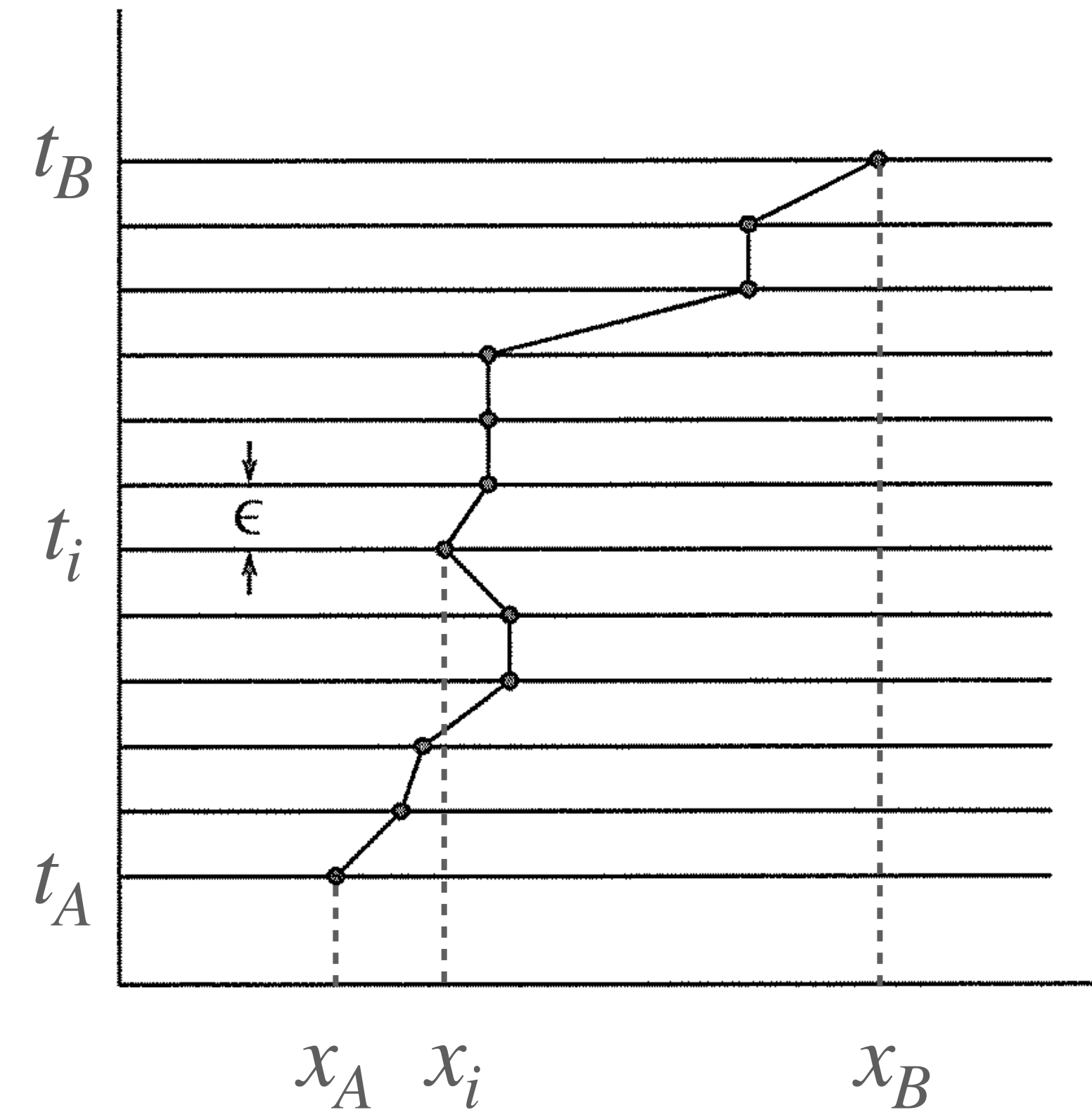
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- Summary:
 $N\epsilon = t_B - t_A,$
 $\epsilon = t_{i+1} - t_i,$
 $t_0 = t_A,$
 $t_N = t_B$
 $x_0 = x_A,$
 $x_N = x_B$

Defining the path integral

Defining the path integral

- Define the sum over all such paths by taking a multiple integral over all x_i coordinate choices

- $$K(x_B, t_B; x_A, t_A) \sim \int \cdots \int \int e^{\frac{i}{\hbar} S[B,A]} dx_1 dx_2 \cdots dx_{N-1}$$

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- $K(x_B, t_B; x_A, t_A) = \lim_{\epsilon \rightarrow 0, N \rightarrow \infty} \frac{1}{C} \int \cdots \int \int e^{\frac{i}{\hbar} S[B,A]} \frac{dx_1}{C} \frac{dx_2}{C} \cdots \frac{dx_{N-1}}{C}$

- $C = \left(\frac{2\pi i \hbar \epsilon}{m} \right)^{\frac{1}{2}}$; Overall normalizing factor is C^{-N}

- $S[B, A] = \int_{t_A}^{t_B} L(x, \dot{x}, t) dt$

Considerations and notation

Considerations and notation

- Note that for the given the path we've defined, the velocities are discontinuous, and therefore the acceleration $\ddot{x}_i$ is formally infinite at each time step t_i !
- A workaround is to define the acceleration as $\ddot{x}_i = \frac{1}{\epsilon}(x_{i+1} - 2x_i + x_{i-1})$, i.e. average over three neighboring points

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- Finally, we can use a shorthand to denote the path integral

- $$K[B, A] = \int_A^B \mathcal{D}x(t) e^{\frac{i}{\hbar} S[B, A]}$$

Path integral for a free particle

Path integral for a free particle

- Path integral is $K(x_B, t_B; x_A, t_A) = \lim_{\epsilon \rightarrow 0} \int \cdots \int dx_1 \cdots dx_{N-1} \left(\frac{2\pi i \hbar \epsilon}{m} \right)^{-\frac{N}{2}} e^{\frac{i}{\hbar} S[B,A]}$
- So we need to calculate the action for each discretized path from
$$S[B, A] = \int_{t_A}^{t_B} L(x, \dot{x}, t) dt$$
- Note: we can get the action for the full path by adding up the contribution from each component of the path, i.e. assuming $t_A < t_C < t_B$, then the action along any path between A and B is
 - $S[B, A] = S[B, C] + S[C, A]$

Path integral for a free particle

Path integral for a free particle

Putting this together with the result of Quiz 1,

$$S[i, i-1] = \frac{m}{2} \frac{(x_i - x_{i-1})^2}{\epsilon}, \text{ and}$$
$$S[B, A] = \sum_{i=1}^N S[i, i-1] = \sum_{i=1}^N \frac{m}{2} \frac{(x_i - x_{i-1})^2}{\epsilon}$$

So,

$$K(B, A) = \lim_{\epsilon \rightarrow 0} \int \cdots \int dx_1 \cdots dx_N \left(\frac{2\pi i \hbar \epsilon}{m} \right)^{-\frac{N}{2}} \exp \left[\frac{im}{2\hbar \epsilon} \sum_{i=1}^N (x_i - x_{i-1})^2 \right]$$

Note this is a ***Gaussian integral***

Gaussian integrals

Gaussian integrals

Gaussian integral: $\int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}$

More generally, $\int_{-\infty}^{+\infty} e^{-ax^2+bx} = \sqrt{\frac{\pi}{a}} e^{b^2/(4a)}$

With complex arguments, $\int_{-\infty}^{+\infty} e^{iax^2+ibx} = \sqrt{\frac{i\pi}{a}} e^{-ib^2/(4a)}$

Gaussian integral proof

Gaussian integral proof

$$\begin{aligned}\left[\int_{-\infty}^{+\infty} e^{-x^2} dx\right]^2 &= \left[\int_{-\infty}^{+\infty} e^{-x^2} dx\right] \left[\int_{-\infty}^{+\infty} e^{-y^2} dy\right] \\&= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} e^{-(x^2+y^2)} dx dy \\&= \int_0^{2\pi} \int_0^{\infty} e^{-r^2} r dr d\theta \\&= 2\pi \int_0^{\infty} e^{-r^2} r dr && (s = r^2) \\&= \pi \int_0^{\infty} e^{-s} ds = -\pi e^{-s} \Big|_0^{\infty} = -\pi(0 - 1) = \pi\end{aligned}$$

Back to the path integral

Back to the path integral

We have terms like this we need to integrate:

$$\left(\frac{m}{2\pi i\hbar\epsilon}\right) \int_{-\infty}^{\infty} \exp \left[\frac{im}{2\hbar\epsilon} [(x_2 - x_1)^2 + (x_1 - x_0)^2] \right] dx_1$$

Let's apply our Gaussian integral formula $\int_{-\infty}^{+\infty} e^{iax^2+ibx} = \sqrt{\frac{i\pi}{a}} e^{-ib^2/(4a)}$

$$\int_{-\infty}^{\infty} \exp \left[\frac{im}{2\hbar\epsilon} (x_2^2 + 2x_1^2 + x_0^2 - 2x_0x_1 - 2x_1x_2) \right] dx_1 = \int_{-\infty}^{\infty} \exp \left[\frac{im}{2\hbar\epsilon} (x_2^2 + 2x_1^2 + x_0^2 - 2x_0x_1 - 2x_1x_2) \right] dx_1$$